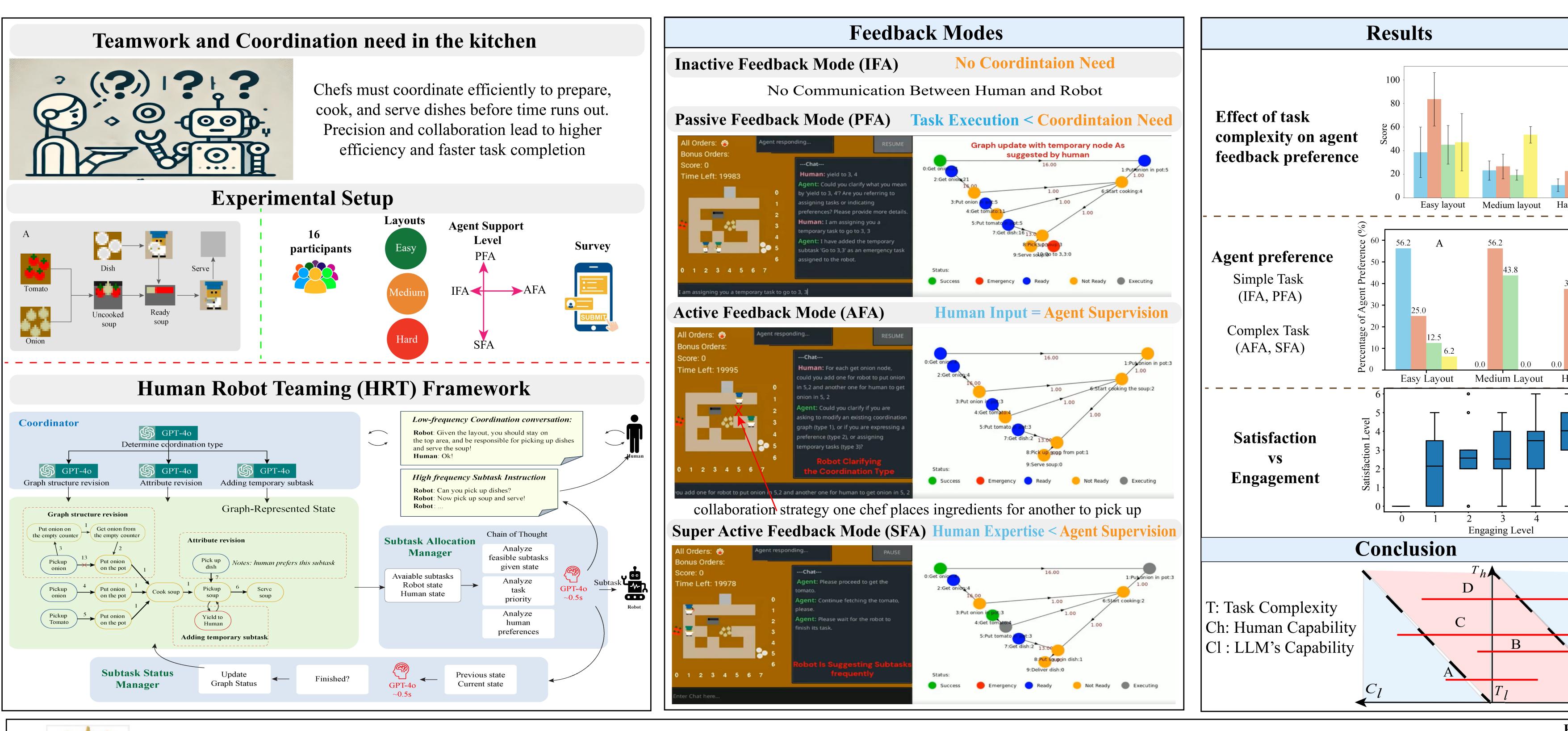


Effect of Adaptive Communication Support on LLM-powered Human-Al Collaboration

Effective human-AI collaboration relies on adaptive communication strategies, yet traditional human-robot interactions often lack the flexibility needed for dynamic tasks. To explore how AI feedback frequency impacts teamwork efficiency, we developed a Human-Robot Teaming Framework with Multi-Modal Language Feedback (HRT-ML) and evaluated it in a simulated Overcooked-AI environment. Through controlled experiments, we found that overly passive agents hinder performance in complex tasks, while excessively active agents overwhelm users with unnecessary feedback, reducing efficiency. By introducing a strategic balance between high-level coordination and subtask-specific feedback, our model enables AI agents to optimize communication dynamically, leading to significant improvements in team efficiency, user satisfaction, and task completion speed.





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